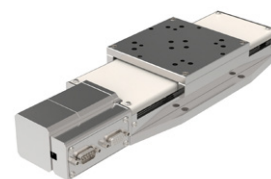
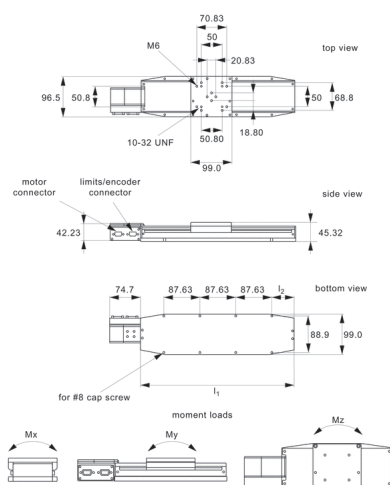




Vacuum Compatible Motorised Stages

high precision

Motorised Linear Stages



L3502

MOTORISED LINEAR STAGES

Material

Aluminium body (6061). Hardened linear guideways, stainless steel Acme lead screw (with internally lubricated anti-backlash nut).

Technical Notes

Operation down to 10^{-6} Torr.

Teflon jacketed wire, fluxless soldered connections. Vacuum compatible motor and limit switches. Low vapour pressure lubricant, blind holes are vented. All parts are thoroughly cleaned followed by latex gloved assembly.

Replace -XXX in part number with the code for your preferred motor type - see second data table for codes and specifications. Easy plug and play system. Controllable from PC or PLC when used in conjunction with a motion controller. Controllers come

with their own software but many pre-existing software packages (such as Labview) can be used.

Can be readily supplied in XY, XZ and XYZ configurations.

Applications - research, semi-conductors, fibre optics, automation etc.

Replace -XXX in part number with the code for your preferred motor type - see second data table for codes and specifications.

Tips

Motor options:

Stepper - Nema 17, high torque, brushless. 0.95 Amp/phase, 5.0 Ohm/phase, 3.1 mH/phase, 1.8°/step.

Intelligent stepper - Nema 17 with a fully programmable motion controller inbuilt (ie no need for an external motion

controller). Two +5 to +24VDC I/O lines. One 10 bit analogue input selectable 0 to +10VDC, 0 to +5VDC. RS422/485 communications. Input voltage +24VDC. Drawings show stepper motor configuration. See special pages for further motor options.

Important Notes

Max. moment loads:

$M_x = 20 \text{ Nm}$

$M_y = 20 \text{ Nm}$

$M_z = 19 \text{ Nm}$

For 50mm travel stage M_a and $M_b = 12 \text{ Nm}$.

For combined stages, add suffixes:

XY - for XY stage

XZ - for XZ stage

XYZ - for XYZ stage

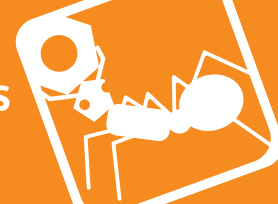
Order No.	Travel	Motor type	Motor code	Accuracy mm $\pm$	Bi-directional repeatability $\pm$	Horizontal load kg max.	Vertical load kg max.	Side load kg max.	Weight kg
L3502.050-STA	50	Stepper	-STA	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-STB	50	Stepper	-STB	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-STC	50	Stepper & enc.	-STC	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-STD	50	Stepper & enc.	-STD	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-IMA	50	Int. stepper	-IMA	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-IMB	50	Int. stepper	-IMB	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-IMC	50	Int. stepper & enc.	-IMC	0,6 μ	10 μ	23	6.5	18	1.36
L3502.050-IMD	50	Int. stepper	-IMD	0,6 μ	10 μ	23	6.5	18	1.36
L3502.100-STA	100	Stepper	-STA	0,6 μ	10 μ	23	6.5	18	2.14
L3502.100-STB	100	Stepper	-STB	0,6 μ	10 μ	23	6.5	18	2.14
L3502.100-STC	100	Stepper & enc.	-STC	0,6 μ	10 μ	23	6.5	18	2.14
L3502.100-STD	100	Stepper & enc.	-STD	0,6 μ	10 μ	23	6.5	18	2.14
L3502.100-IMA	100	Int. stepper	-IMA	0,6 μ	10 μ	23	6.5	18	2.14



Automotion
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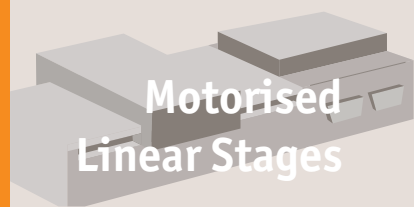


Order No.	Travel	Motor type	Motor code	Accuracy mm ±	Bi-directional repeatability ±	Horizontal load kg max.	Vertical load kg max.	Side load kg max.	Weight kg
L3502.100-IMB	100	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	2.14
L3502.100-IMC	100	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	2.14
L3502.100-IMD	100	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	2.14
L3502.150-STA	150	Stepper	-STA	0,6µ	10µ	23	6.5	18	2.41
L3502.150-STB	150	Stepper	-STB	0,6µ	10µ	23	6.5	18	2.41
L3502.150-STC	150	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	2.41
L3502.150-STD	150	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	2.41
L3502.150-IMA	150	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	2.41
L3502.150-IMB	150	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	2.41
L3502.150-IMC	150	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	2.41
L3502.150-IMD	150	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	2.41
L3502.200-STA	200	Stepper	-STA	0,6µ	10µ	23	6.5	18	2.59
L3502.200-STB	200	Stepper	-STB	0,6µ	10µ	23	6.5	18	2.59
L3502.200-STC	200	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	2.59
L3502.200-STD	200	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	2.59
L3502.200-IMA	200	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	2.59
L3502.200-IMB	200	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	2.59
L3502.200-IMC	200	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	2.59
L3502.200-IMD	200	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	2.59
L3502.250-STA	250	Stepper	-STA	0,6µ	10µ	23	6.5	18	2.86
L3502.250-STB	250	Stepper	-STB	0,6µ	10µ	23	6.5	18	2.86
L3502.250-STC	250	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	2.86
L3502.250-STD	250	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	2.86
L3502.250-IMA	250	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	2.86
L3502.250-IMB	250	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	2.86
L3502.250-IMC	250	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	2.86
L3502.250-IMD	250	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	2.86
L3502.300-STA	300	Stepper	-STA	0,6µ	10µ	23	6.5	18	3.13
L3502.300-STB	300	Stepper	-STB	0,6µ	10µ	23	6.5	18	3.13
L3502.300-STC	300	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	3.13
L3502.300-STD	200	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	3.13
L3502.300-IMA	250	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	3.13
L3502.300-IMB	300	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	3.13
L3502.300-IMC	350	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	3.13
L3502.300-IMD	400	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	3.13
L3502.350-STA	350	Stepper	-STA	0,6µ	10µ	23	108.3	18	3.41
L3502.350-STB	350	Stepper	-STB	0,6µ	10µ	23	108.3	18	3.41
L3502.350-STC	350	Stepper & enc.	-STC	0,6µ	10µ	23	108.3	18	3.41
L3502.350-STD	350	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	3.41
L3502.350-IMA	350	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	3.41
L3502.350-IMB	350	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	3.41
L3502.350-IMC	350	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	3.41
L3502.350-IMD	350	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	3.41
L3502.400-STA	400	Stepper	-STA	0,6µ	10µ	23	6.5	18	3.68
L3502.400-STB	400	Stepper	-STB	0,6µ	10µ	23	6.5	18	3.68
L3502.400-STC	400	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	3.68
L3502.400-STD	400	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	3.68
L3502.400-IMA	400	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	3.68
L3502.400-IMB	400	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	3.68
L3502.400-IMC	400	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	3.68
L3502.400-IMD	400	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	3.68
L3502.500-STA	500	Stepper	-STA	0,6µ	10µ	23	6.5	18	3.95
L3502.500-STB	500	Stepper	-STB	0,6µ	10µ	23	6.5	18	3.95
L3502.500-STC	500	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	3.95
L3502.500-STD	500	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	3.95
L3502.500-IMA	500	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	3.95
L3502.500-IMB	500	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	3.95
L3502.500-IMC	500	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	3.95



Vacuum Compatible Motorised Stages

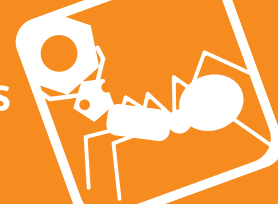
high precision



Motorised Linear Stages

Order No.	Travel	Motor type	Motor code	Accuracy mm ±	Bi-directional repeatability ±	Horizontal load kg max.	Vertical load kg max.	Side load kg max.	Weight kg
L3502.500-IMD	500	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	3.95
L3502.600-STA	600	Stepper	-STA	0,6µ	10µ	23	6.5	18	4.23
L3502.600-STB	600	Stepper	-STB	0,6µ	10µ	23	6.5	18	4.23
L3502.600-STC	600	Stepper & enc.	-STC	0,6µ	10µ	23	6.5	18	4.23
L3502.600-STD	600	Stepper & enc.	-STD	0,6µ	10µ	23	6.5	18	4.23
L3502.600-IMA	600	Int. stepper	-IMA	0,6µ	10µ	23	6.5	18	4.23
L3502.600-IMB	600	Int. stepper	-IMB	0,6µ	10µ	23	6.5	18	4.23
L3502.600-IMC	600	Int. stepper & enc.	-IMC	0,6µ	10µ	23	6.5	18	4.23
L3502.600-IMD	600	Int. stepper	-IMD	0,6µ	10µ	23	6.5	18	4.23

Order No.	Lead screw pitch	Speed mm/s max.	I ₁	I ₂	Resolution ±
L3502.050-STA	1.5875	12.0	176	44.5	0,03µ
L3502.050-STB	6.35	50.0	176	44.5	0,13µ
L3502.050-STC	1.5875	12.0	176	44.5	0,4µ
L3502.050-STD	6.35	50.0	176	44.5	1,6µ
L3502.050-IMA	1.5875	12.0	176	44.5	0,4µ
L3502.050-IMB	6.35	12.0	176	44.5	1,6µ
L3502.050-IMC	1.5875	25.0	176	44.5	0,4µ
L3502.050-IMD	6.35	50.0	176	44.5	1,6µ
L3502.100-STA	1.5875	12.0	226	68.9	0,03µ
L3502.100-STB	6.35	50.0	226	68.9	0,13µ
L3502.100-STC	1.5875	12.0	226	68.9	0,4µ
L3502.100-STD	6.35	50.0	226	68.9	1,6µ
L3502.100-IMA	1.5875	12.0	226	68.9	0,4µ
L3502.100-IMB	6.35	12.0	226	68.9	1,6µ
L3502.100-IMC	1.5875	25.0	226	68.9	0,4µ
L3502.100-IMD	6.35	50.0	226	68.9	1,6µ
L3502.150-STA	1.5875	12.0	277	44.5	0,03µ
L3502.150-STB	6.35	50.0	277	68.9	0,13µ
L3502.150-STC	1.5875	12.0	277	94.3	0,4µ
L3502.150-STD	6.35	50.0	277	119.7	1,6µ
L3502.150-IMA	1.5875	12.0	277	57.5	0,4µ
L3502.150-IMB	6.35	12.0	277	82.7	1,6µ
L3502.150-IMC	1.5875	25.0	277	108.3	0,4µ
L3502.150-IMD	6.35	50.0	277	133.7	1,6µ
L3502.200-STA	1.5875	12.0	327	119.7	0,03µ
L3502.200-STB	6.35	50.0	327	119.7	0,13µ
L3502.200-STC	1.5875	12.0	327	119.7	0,4µ
L3502.200-STD	6.35	50.0	327	119.7	1,6µ
L3502.200-IMA	1.5875	12.0	327	119.7	0,4µ
L3502.200-IMB	6.35	12.0	327	119.7	1,6µ
L3502.200-IMC	1.5875	25.0	327	119.7	0,4µ
L3502.200-IMD	6.35	50.0	327	119.7	1,6µ
L3502.250-STA	1.5875	12.0	378	57.5	0,03µ
L3502.250-STB	6.35	50.0	378	57.5	0,13µ
L3502.250-STC	1.5875	12.0	378	57.5	0,4µ
L3502.250-STD	6.35	50.0	378	57.5	1,6µ
L3502.250-IMA	1.5875	12.0	378	57.5	0,4µ
L3502.250-IMB	6.35	12.0	378	57.5	1,6µ
L3502.250-IMC	1.5875	25.0	378	57.5	0,4µ
L3502.250-IMD	6.35	50.0	378	57.5	1,6µ
L3502.300-STA	1.5875	12.0	429	82.7	0,03µ
L3502.300-STB	6.35	50.0	429	82.7	0,13µ
L3502.300-STC	1.5875	12.0	429	82.7	0,4µ
L3502.300-STD	6.35	50.0	429	82.7	1,6µ
L3502.300-IMA	1.5875	12.0	429	82.7	0,4µ
L3502.300-IMB	6.35	12.0	429	82.7	1,6µ
L3502.300-IMC	1.5875	25.0	429	82.7	0,4µ
L3502.300-IMD	6.35	50.0	429	82.7	1,6µ
L3502.350-STA	1.5875	12.0	480	44.5	0,03µ
L3502.350-STB	6.35	50.0	480	68.9	0,13µ
L3502.350-STC	1.5875	12.0	480	94.3	0,4µ
L3502.350-STD	6.35	50.0	480	108.3	1,6µ



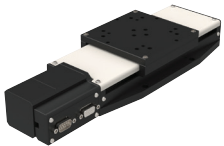
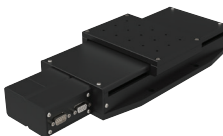
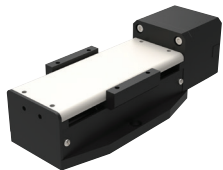
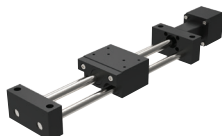
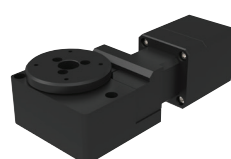
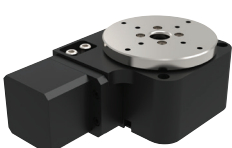
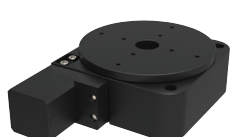
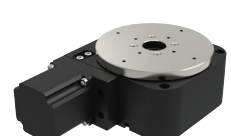
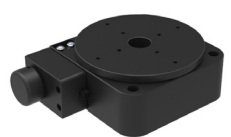
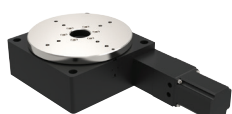
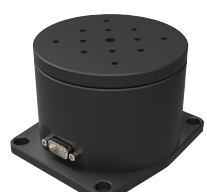
Order No.	Lead screw pitch	Speed mm/s max.	l_1	l_2	Resolution $\pm$
L3502.350-IMA	1.5875	12.0	480	108.3	0,4 μ
L3502.350-IMB	6.35	12.0	480	108.3	1,6 μ
L3502.350-IMC	1.5875	25.0	480	108.3	0,4 μ
L3502.350-IMD	6.35	50.0	480	108.3	1,6 μ
L3502.400-STA	1.5875	12.0	531	133.7	0,03 μ
L3502.400-STB	6.35	50.0	531	133.7	0,13 μ
L3502.400-STC	1.5875	12.0	531	133.7	0,4 μ
L3502.400-STD	6.35	50.0	531	133.7	1,6 μ
L3502.400-IMA	1.5875	12.0	531	133.7	0,4 μ
L3502.400-IMB	6.35	12.0	531	133.7	1,6 μ
L3502.400-IMC	1.5875	25.0	531	133.7	0,4 μ
L3502.400-IMD	6.35	50.0	531	133.7	1,6 μ
L3502.500-STA	1.5875	12.0	632	185.5	0,03 μ
L3502.500-STB	6.35	50.0	632	185.5	0,13 μ
L3502.500-STC	1.5875	12.0	632	185.5	0,4 μ
L3502.500-STD	6.35	50.0	632	185.5	1,6 μ
L3502.500-IMA	1.5875	12.0	632	185.5	0,4 μ
L3502.500-IMB	6.35	12.0	632	185.5	1,6 μ
L3502.500-IMC	1.5875	25.0	632	185.5	0,4 μ
L3502.500-IMD	6.35	50.0	632	185.5	1,6 μ
L3502.600-STA	1.5875	12.0	734	235.3	0,03 μ
L3502.600-STB	6.35	50.0	734	235.3	0,13 μ
L3502.600-STC	1.5875	12.0	734	235.3	0,4 μ
L3502.600-STD	6.35	50.0	734	235.3	1,6 μ
L3502.600-IMA	1.5875	12.0	734	235.3	0,4 μ
L3502.600-IMB	6.35	12.0	734	235.3	1,6 μ
L3502.600-IMC	1.5875	25.0	734	235.3	0,4 μ
L3502.600-IMD	6.35	50.0	734	235.3	1,6 μ



Motorised Linear & Rotary Stages

Overview

Positioning Stages

L3500 Medium duty motorised stage 	L3504 Heavy-duty motorised stage 	L3505 Motorised linear stage 	L3506 Miniature motorised stage 
L3508 Motorised linear stage 	L3510 Motorised linear stage 	L3521 Single axis stepper controller 	L3522 Two axes stepper controller 
L3524 Multi-axes stepper controller 	L3525 Single axis servo controller 	L3550 Motorised rotary stage Ø50 	L3552 Motorised rotary stage Ø75 
L3554 Motorised rotary stage Ø75 	L3556 Motorised rotary stage Ø125 	L3558 Motorised rotary stage Ø125 	L3559 Manual rotary stage Ø125 
L3562 Motorised rotary stage Ø200 	L3569 High speed rotary table 	L3591 Vertical lift stage motorised 	L3592 Vertical lift stage motorised 

MOTORISED LINEAR STAGES



Our motorised linear stages are precise, heavy duty and available from 25mm stroke to 800mm.

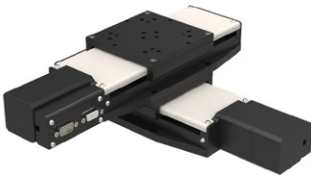
They can be easily controlled either with an Intelligent motor (this is a motor with an inbuilt driver and controller) or with a motor and one of our motion controller stages.

Programming for both the intelligent motor (less expensive) and the motion controllers is very simple and we provide free software and sample source code for Labview, VB, C++, OSX etc. It is also possible to download a stand-alone programme to the device so it can run independently of a host.

We also offer a Joystick controller.

The stages can be readily supplied in X, XY, XZ and XYZ configurations and can also be used with our range of rotary tables (L3550 to L3562).

XY Assembly



XY Assembly



XY Assembly



Using intelligent motors

- RS-485 - USB connection.
- Can run independently from host.
- Joystick control option

Using motion controllers

- RS-485 - USB connection.
- Can run independently from host.
- Joystick control option



Motorised Stages

Stepper + servo motors

Positioning Stages

Positioning Stages from Automotion Components

MOTORISED LINEAR STAGES

Stepper limitations

For all of their advantages, stepper motors have a number of limitations which can cause significant implementation and operational issues depending on your application. Stepper motors do not have any reserve power. In fact, stepper motors lose a significant amount of their torque as they approach their maximum driver speed. A loss of 80% of the rated torque at 90% of the maximum speed is typical.

Stepper motors are also not as good as servo motors in accelerating a load. Attempting to accelerate a load too fast where the stepper cannot generate enough torque to move to the next step before the next drive pulse will result in a skipped step and a loss in position. If positional accuracy is essential, either the load on the motor must never exceed its torque or the stepper must be combined with a position encoder to ensure positional accuracy.

Stepper motors may also suffer from vibration and resonance problems. At certain speeds, partially depending on the load dynamics, they may resonate and be unable to drive the load. This may result in skipped steps, stalled motors, excessive vibration and noise.

Servo limitations

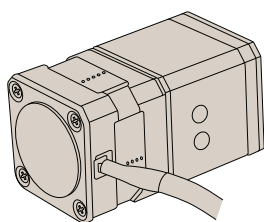
Servo motors are capable of delivering more power than stepper motors, but do require much more complex drive circuitry and positional feedback for accurate positioning. Servo motors are also much considerably expensive than stepper motors and are often harder to find. Servo motors often require gear boxes, especially for lower speed operation.

The requirement for a gearbox and a position encoder makes servo motor designs more mechanically complex and increases the maintenance requirements for the system. To top it all off, servo motors are more expensive than stepper motors before adding on the cost of a position encoder.

Summary

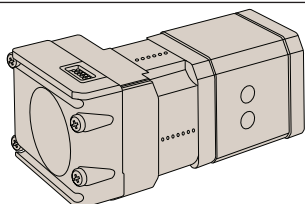
Selecting the best motor for your application depends on a few key design criteria for your system including cost, positional accuracy requirements, torque requirements, drive power availability, and acceleration requirements. Overall, servo motors are best for high speed, high torque applications while stepper motors are better suited for lower acceleration, high holding torque applications as well as generally being less expensive and easier to control.

Motor options



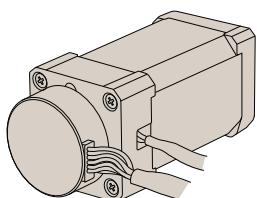
Stepper motor

- Standard
- With rotary encoder (1000 line)



Intelligent stepper motor

- Standard
- With rotary encoder (512 line)



Servo motor

- Standard
- With rotary encoder (1000 line)