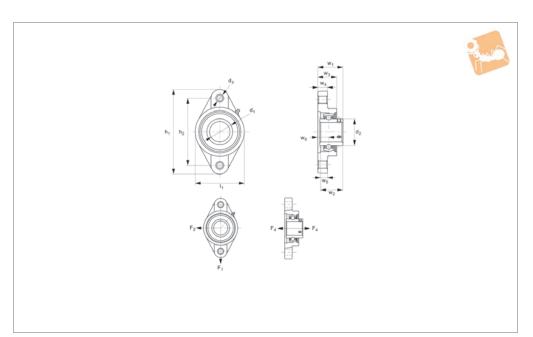


Thermoplastic Oval Flanged Unit

two point flange







L1878

Material

Thermoplastic (PBT) housing, with smooth surfaces. Stainless steel bearings (440C) with 2RS seals and sleeves for fixing bolts. Bearing lubricated with food grade grease.

Technical Notes

Self-aligning bearing units.

Temperature range for bearings: -15°C to +120°C.

Resistant to a wide range of chemicals. Provide good protection against bacterial contamination.

Open and closed protection caps available (see our part L1869).

Tips

Shaft retention with two set screws (at 120° offset).

Used with h6 tolerance shafts (see our part no.s L1770-L1776).

For protective end caps see L1879.

Order No.	d ₁ for h6	I ₁	w_1	w_2	w ₃	W_4	w_5	w ₆	d ₂	d ₃	Weight kg
L1878.020	20	65	33.7	31.0	26.5	11.4	12.7	15.4	29.0	11	0.25
L1878.025	25	70	36.7	34.0	29.7	13.5	14.3	17.0	34.0	11	0.30
L1878.030	30	80	41.2	38.1	30.5	13.3	15.9	19.0	40.5	11	0.45
L1878.035	35	90	43.4	42.9	32.8	16.1	17.5	18.0	48.0	13	0.67
L1878.040	40	100	51.7	49.2	37.5	20.0	19.0	21.5	53.0	14	0.88

Order No.	h ₁	h ₂ +0 -0.8	Speed rpm max.	Static radial bearing load C_0 kN max.	Housing load F ₁ kN max.	Housing load F ₂ kN max.	Axial load F ₃ kN max.	Set screw size	Torque screw to Nm
L1878.020	130	90	7400	5.3	0.9	2.2	0.7	M6x1	3.9
L1878.025	130	99	6200	6.3	1.5	2.2	0.7	M6x1	3.9
L1878.030	148	117	5300	9.0	1.6	2.9	1.0	M6x1	3.9
L1878.035	163	130	4500	12.3	2.0	3.2	1.4	M8x1	8.3
L1878.040	175	144	4000	14.3	2.0	3.2	1.4	M8x1	8.3



Support

Self-Aligning Bearing Units

Overview



Housing material options

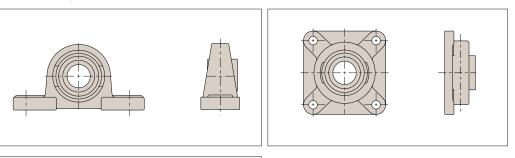


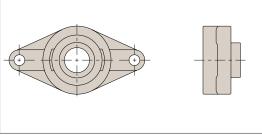
Cast iron housing Standard version, passivated and painted Ø12-120mm.

Stainless steel housing Stainless AISI 304, Ø12-60mm.

Thermoplastic housing Food grade applications, smooth PBT resin material, Ø20-40mm.

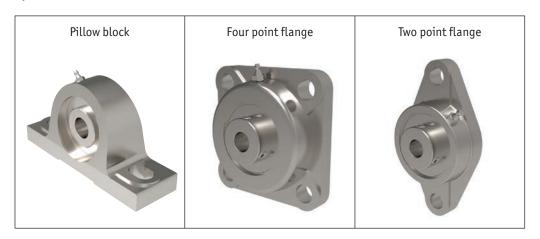
Pillow Bearings





Use with Automotion linear shafts L1770-L1774

Options



Self-Aligning Bearing Units

Technical



ring Supports from Automotion Components

For cast iron housings

- Single row radial contact self-aligning bearings (steel 100Cr6).
- Re-lubricatable.
- Fixing to shaft via set screw.
- Operating temperature range -20° to +100°.

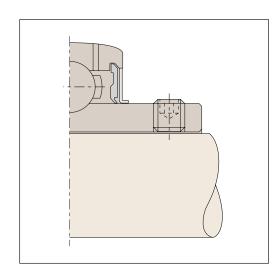
For stainless & thermoplastic housings

- Single row radial contact self-aligning bearings (stainless steel AISI 440C), stainless steel cage.
- Lubricated with food grade grease.
- Fixing to shaft via set screw.

Shaft fixing set screw

2 set screws at 120° with hexagon socket and knurled cup point, recommended shaft tolerance h6/h7.

Set screw	Max. tightening torque (Nm)	Hexagon socket A/F
M5 x 0,8	3,5	2,5
M6 x 1	5,5	3,0
M8 x 1	11,5	4,0
M10 x 1,25	22,0	5,0
M12 x 1,25	33,0	6,0
M14 x 1,5	42,0	7,0
M16 x 1,5	64,0	8,0
M18 x 1,5	75,0	9,0
M20 x 1,5	120,0	10,0

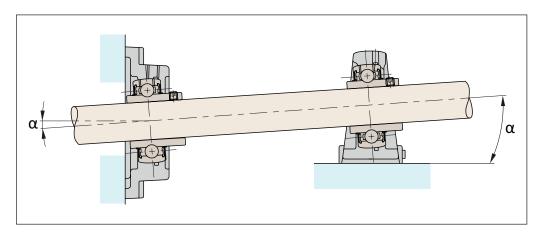


Lubrication

Our units are lubricated for life. If re-lubrication is necessary (because of severe operating conditions), use a lithium soap base with a viscosity of 100mm²/s at 40°C.

Installation

Shaft misalignment is compensated to a certain degree by the shaft-aligning bearings.



If re-lubrication required

 $\alpha = \pm 2^{\circ}$

If no re-lubrication

 $\alpha = \pm 5^{\circ}$

When using protective end caps

 $\alpha = \pm 5^{\circ}$



earing Supports from Automotion Components



Equivalent load ratings

Support



The radial loads of the cast iron bearing supports are limited by the bearings themselves - the housings can withstand the maximum loads.

Please see the part numbers for dynamic and static radial loads. The maximum axial loads are 50% of the maximum static radial loads. The standard bearing have a C3 clearance.

Bore non (m	ninal size m)	Radial bearing clearance (μ)		
Above	Up to	Min.	Max.	
10	18	11	25	
18	24	13	28	
24	30	13	28	
30	40	15	33	
40	50	18	36	
50	65	23	43	
65	80	25	51	
80	100	30	58	
100	120	36	66	
120	140	41	81	

When choosing a suitable bearing size – this depends on the load and speed required.

If the load acts mainly whilst the bearing rotates, then it is a dynamic load, if it acts mainly during no movement or low speeds, then it is a static load.

The maximum for both of these, for each bearing, is shown in the part tables.

Dynamic equivalent loads:

For some situations the bearing will have to withstand both radial and axial loads and we then need to calculate an equivalent dynamic load using the following equation:

$$L = X \bullet F_r + Y \bullet F_a$$
 (kN)

Dynamic equivalent load (kN)

Actual radial load (kN)

Actual axial load (kN)

Χ Radial factor

Axial factor

Load ratio table 1:

F _a	e	F _a F _r	≤e	$\frac{F_a}{F_r} > e$		
-Or		Х	Y	Х	Y	
0,014	0,19				2,30	
0,028	0,22				1,99	
0,056	0,26				1,71	
0,084	0,28				1,55	
0,110	0,30	1	0	0,56	1,45	
0,170	0,34				1,31	
0,280	0,38				1,15	
0,420	0,42				1,04	
0,560	0,44				1,00	

Limiting value

Radial static load rating (see dimension tables for ball bearing units)



Bearing Units

Technical loads + life



earing Supports from Automotion Components

Static equivalent loads

For situations where there are radial and axial loads on the static or slow moving bearings:

$$P_0 = X_0 \bullet F_r + Y_0 \bullet F_a$$
 (kN)

$$P_0 = F_r$$
 if $\frac{F_a}{F_r} \le 0.8$

For all bearing inserts the following applies: = Static equivalent load (kN)

Static radial factorStatic axial factor Static radial factor

Using the ratio fs, it can be checked if sufficient static dimensioning for the insert has been ensured:

 $fs = \frac{C_{or}}{p_o}$

Some standard values are:

Minimal demands for running smoothness and rotating movement 0.7

occasional rotating bearing, normal demands for running 1.0

smoothness, high demands for running smoothness

It should be noted that this ratio does not provide any assurance against a break or similar, but instead it is assurance against excessive local deformation in the rolling contact (ball/raceway).

Calculating bearing life

When calculating bearing life for bearing units, the following applies:

$$L_{10} = \left(\frac{C_r}{p}\right)^3$$
 (10⁶ revolutions)

If the bearing life should be specified in hours, the following applies:

$$L_{10h} = \left(\frac{C_r}{p}\right)^3 \cdot \frac{10^6}{60n}$$
 (h)

= speed (min⁻¹)

