

L1743

LINEAR BEARINGS

Material

Hardened and ground body from bearing steel - nickel plated.
Stainless steel balls 440C.
Floating plate feature offers self-alignment and clearance adjustment.
Single body resin retainer (POM).
Supplied with nitrile rubber (NBR) end seals -UU as standard.

and 27 x the travel life of conventional linear bushings.
They offer self-alignment - prolonging travel life by reducing the friction between shaft and balls.
For use with hardened shafts only (see part nos. L1770 - L1772) - tolerance h6.
Perpendicularity A is better than 15μ.
Temperature range: -20°C to +80°C.

stainless steel bearing balls provide a good degree of corrosion protection. d_2 is the dimension before the bush has been slotted.

Technical Notes

The superball series has 3 x the load rating

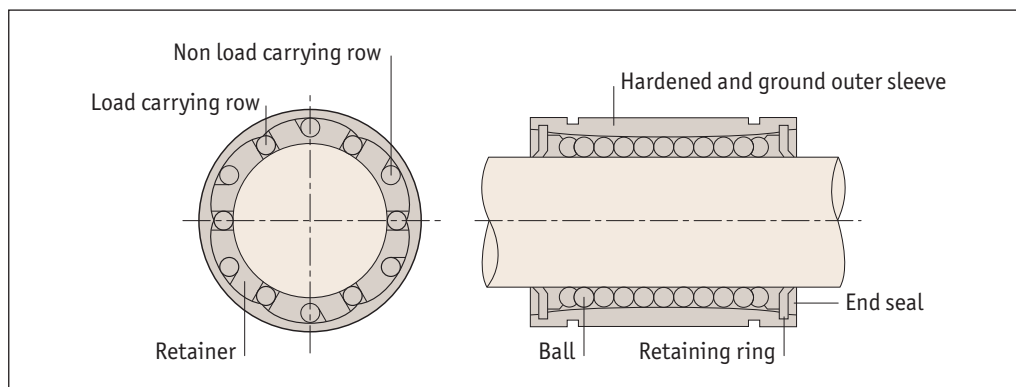
Tips

The nickel plated bearing plates and the

Order No.	d_1 tol. h6	d_2 tol. h6	l_1 ± 0.2	l_2 ± 0.2	l_3 min.	Dyn. load C N max.	w_1	α °	Static load C_0 N max.	Weight g
L1743.012	12	22	32	22.7	1.35	1260	6.5	66	1290	18
L1743.016	16	26	36	24.7	1.35	1320	9.0	68	1640	22
L1743.020	20	32	45	31.3	1.65	1720	9.0	55	2630	51
L1743.025	25	40	58	43.8	1.90	2850	11.5	57	3910	102
L1743.030	30	47	68	81.8	1.90	2900	14.0	57	4850	155
L1743.040	40	62	80	60.4	2.20	5900	19.5	56	6700	300
L1743.050	50	75	100	77.4	2.70	8100	22.5	54	11700	480



Linear ball bushings



Applications

- Computers and peripheral equipment.
- Recording equipment.
- Linear motion systems.
- Multi-axis drilling machine.
- Printing machines.
- Food packaging machines.
- Punching presses.
- Tool grinders.
- Assembly systems.
- Card selectors.

Interchangeability

Our linear bushing systems are designed to have full interchangeability, with other manufacturers' parts. **For shafting see part numbers L1770 to L1785.**

High precision retainer

The single body retainer guides 4-6 ball circuits. It precisely guides the balls with a smooth motion.

Tolerance of housing bore

Normal fit is standard, pressed fit is for without clearance.

Type	Case	
Part no.	Normal fit	Pressed fit
L1706 to L1733	H7	K6, J6
L1706... ⁻¹ to L1733... ⁻¹	H7	J7

Rigid outer sleeve

The hardened and precisely ground outer sleeve is made of bearing steel.

L1750 bushing carriages

Consists of light aluminium case and L1706 type linear bushing, so the installation can be finished simply by bolting. Longer life can be obtained by adjusting the orientation of the ball circuits in the linear carriage element against the direction of load.

Tolerance of shaft

Type	Shaft	
Part no.	Normal fit	Tight fit
L1706 to L1733	h6	k6
L1706... ⁻¹ to L1733... ⁻¹	f6, g6	h6



Technical Information

Load rating important information



LINEAR BEARINGS

Basic dynamic load rating C

The basic dynamic load rating is defined as the constant load both in direction and magnitude under which a group of identical linear bushings are individually operated. 90% of the units can travel 50Km without failing due to rolling contact fatigue.

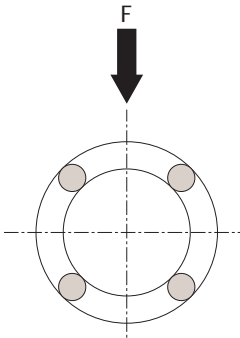
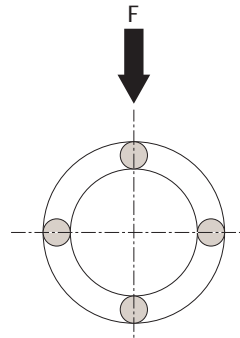
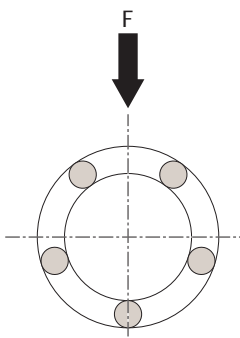
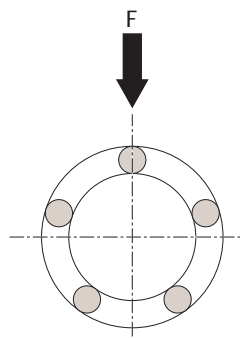
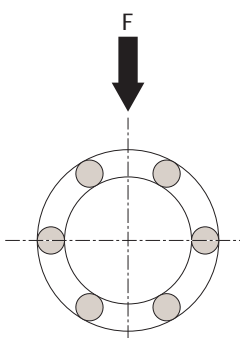
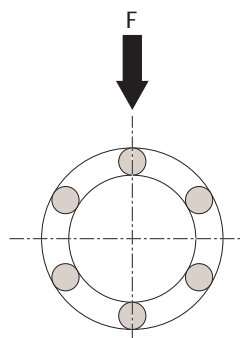
Basic static load rating C₀

If a linear bushing is subject to an excessive load or impact, a permanent deformation occurs between the raceway and the rolling element. The basic static load rating is defined as the static load that gives a prescribed constant contact stress at the centre of the contact area between the rolling element and raceway receiving the maximum load.

Relationships between load ratings and the position of ball circuits

Load ratings of linear bushing are affected by the position of the ball circuits as shown below.

Load ratings and orientation of balls.

No of ball rows	Orientation of balls	
	Maximum load rating	Minimum load rating
4		
	$F = 1.41 \times C$	$F = C$
5		
	$F = 1.46 \times C$	$F = C$
6		
	$F = 1.26 \times C$	$F = C$



When designing a linear motion system it is necessary to consider how the application will affect performance. The following examples demonstrate how the position of the load and the centre of gravity can influence product selection. When evaluating your application, review each of the forces acting on your system and determine the product that best suits your needs.

Horizontal application

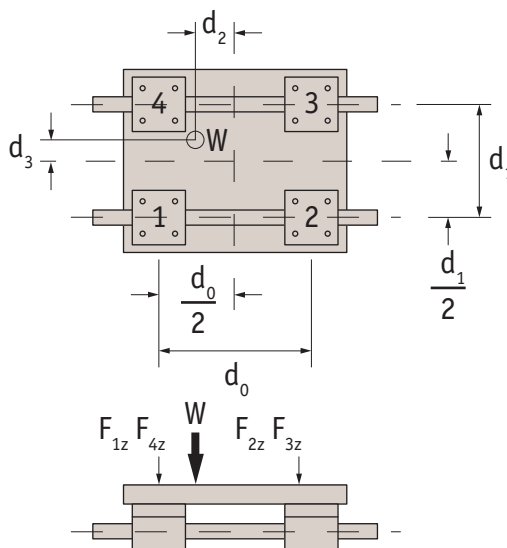
For uniform speed or when stopped.

$$F_{1z} = \frac{W}{4} + \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) - \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$

$$F_{2z} = \frac{W}{4} - \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) - \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$

$$F_{3z} = \frac{W}{4} - \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) + \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$

$$F_{4z} = \frac{W}{4} + \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) + \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$



Horizontal application

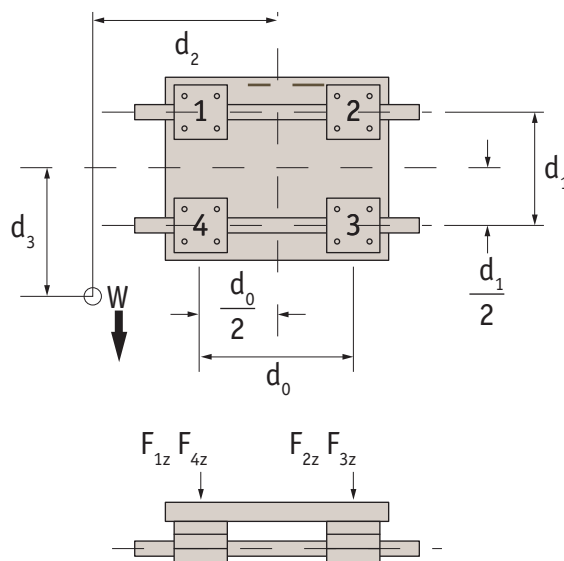
For uniform speed or when stopped.

$$F_{1z} = \frac{W}{4} + \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) - \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$

$$F_{2z} = \frac{W}{4} - \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) - \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$

$$F_{3z} = \frac{W}{4} - \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) + \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$

$$F_{4z} = \frac{W}{4} + \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right) + \left(\frac{W}{2} \cdot \frac{d_3}{d_1} \right)$$





Technical Information

Load rating important information

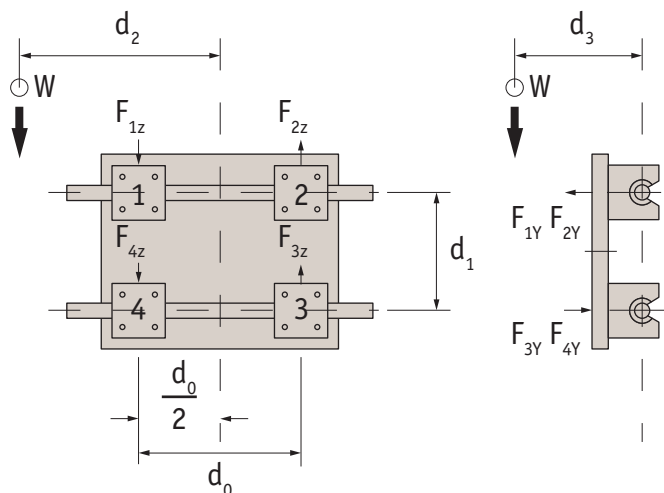
Linear Ball Bushings

LINEAR BEARINGS

$$F_{1Y} \sim F_{4Y} = \left(\frac{W}{2} \cdot \frac{d_3}{d_0} \right)$$

$$F_{1Z} = F_{4Z} = \frac{W}{4} + \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right)$$

$$F_{2Z} = F_{3Z} = \frac{W}{4} + \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right)$$



Side mounted application

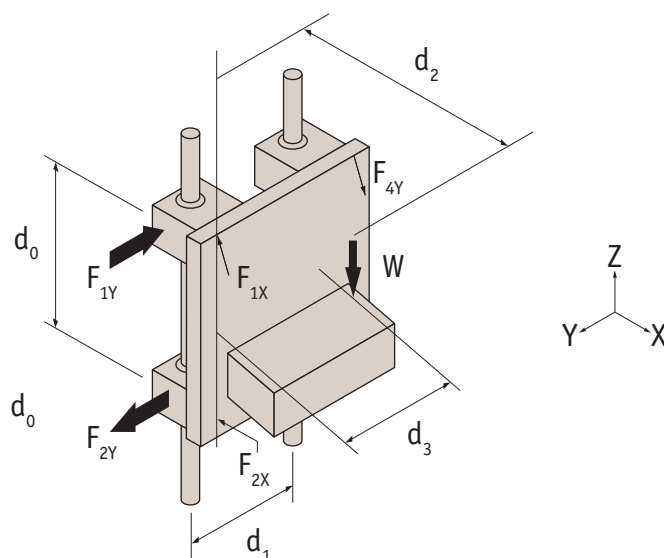
For uniform speed or when stopped.

$$F_{1X} \sim F_{4X} = \left(\frac{W}{2} \cdot \frac{d_2}{d_0} \right)$$

$$F_{1Y} \sim F_{4Y} = \left(\frac{W}{2} \cdot \frac{d_3}{d_0} \right)$$

$$F_{1X} + F_{4X} \sim F_{2X} + F_{3X}$$

$$F_{1Y} + F_{4Y} \sim F_{2Y} + F_{3Y}$$



Vertical application

For uniform speed or when stopped. On start up/stop the load varies due to inertia in the system.